

BFS for Single Source Shortest Path

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Objectives

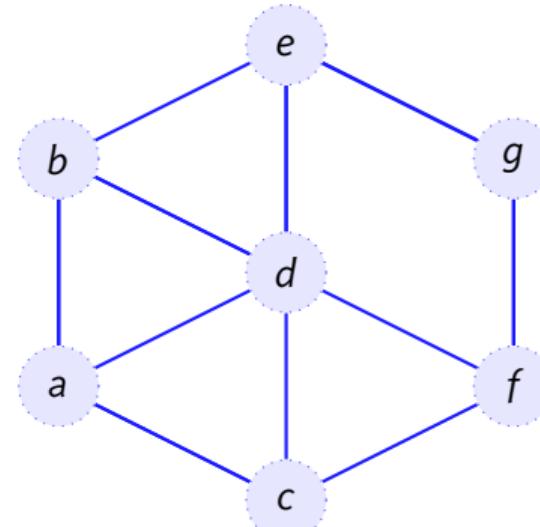
Your Objectives:

- ▶ Implement SSSP using BFS

The Algorithm

- ▶ Use this if your graph is unweighted
- ▶ Create a distance array and a parent array

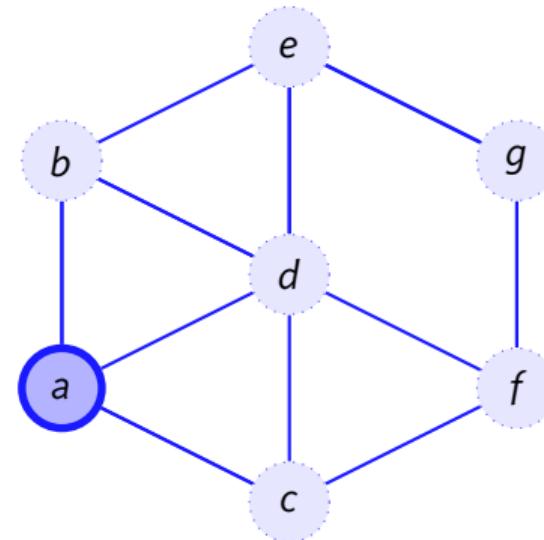
| | a | b | c | d | e | f | g |
|--------|---|---|---|---|---|---|---|
| Dist | | | | | | | |
| Parent | | | | | | | |



The Algorithm

- ▶ Use this if your graph is unweighted
- ▶ Create a distance array and a parent array

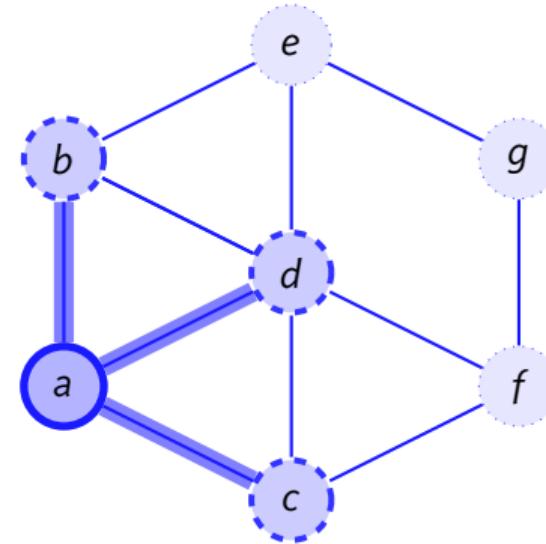
| | a | b | c | d | e | f | g |
|--------|---|----------|----------|----------|----------|----------|----------|
| Dist | 0 | ∞ | ∞ | ∞ | ∞ | ∞ | ∞ |
| Parent | - | - | - | - | - | - | - |



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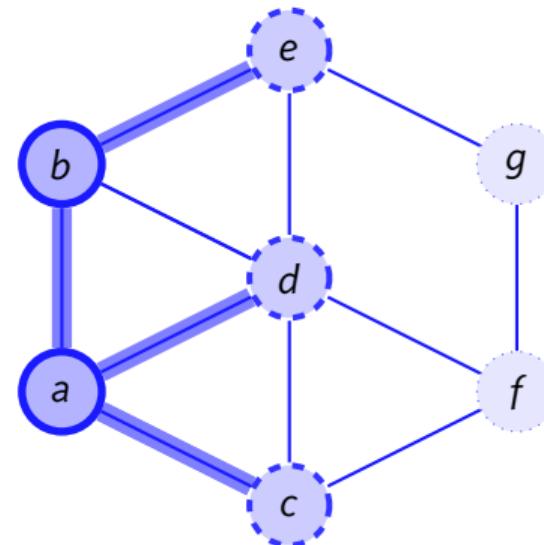
| | | | | | | | |
|--------|---|---|---|---|----------|----------|----------|
| | a | b | c | d | e | f | g |
| Dist | 0 | 1 | 1 | 1 | ∞ | ∞ | ∞ |
| Parent | - | a | a | a | - | - | - |



The Algorithm

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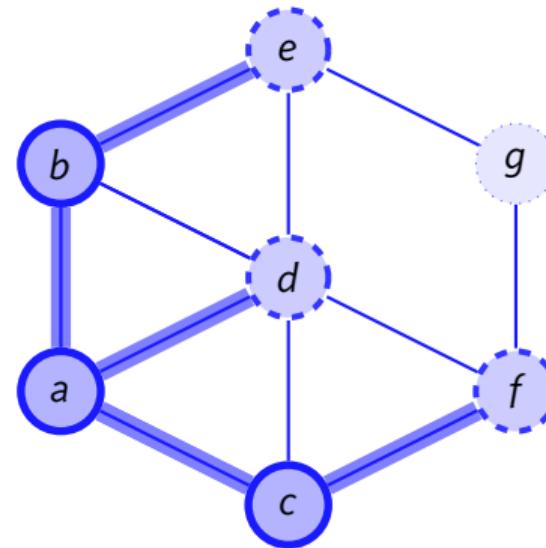
| | a | b | c | d | e | f | g |
|--------|---|---|---|---|---|----------|----------|
| Dist | 0 | 1 | 1 | 1 | 2 | ∞ | ∞ |
| Parent | - | a | a | a | b | - | - |



The Algorithm

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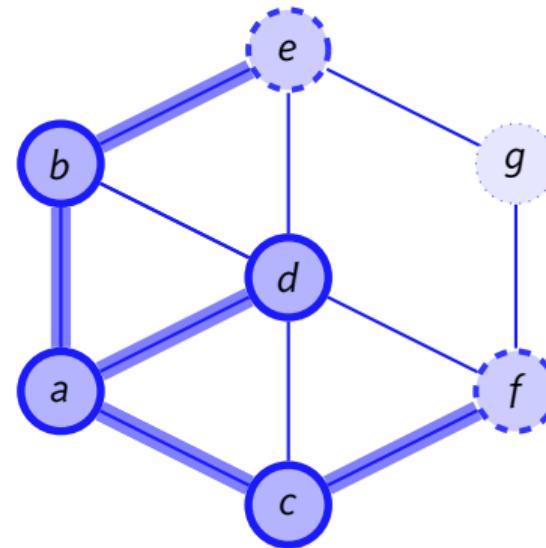
| | | | | | | | |
|--------|---|---|---|---|---|---|----------|
| | a | b | c | d | e | f | g |
| Dist | 0 | 1 | 1 | 1 | 2 | 2 | ∞ |
| Parent | - | a | a | a | b | c | - |



The Algorithm

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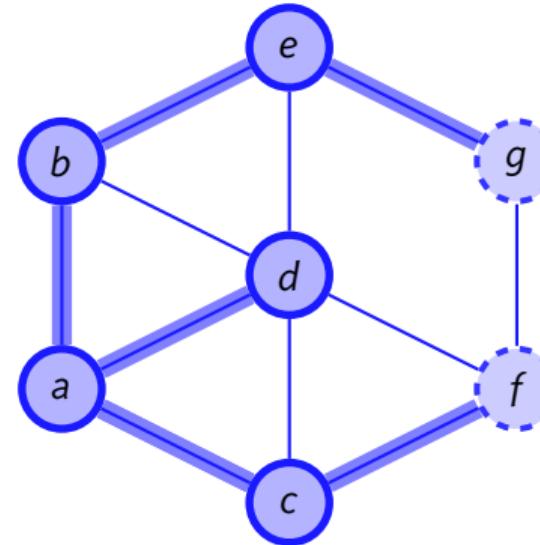
| | | | | | | | |
|--------|---|---|---|---|---|---|----------|
| | a | b | c | d | e | f | g |
| Dist | 0 | 1 | 1 | 1 | 2 | 2 | ∞ |
| Parent | - | a | a | a | b | c | - |



The Algorithm

- ▶ Use this if your graph is unweighted
- ▶ Create a distance array and a parent array

| | | | | | | | |
|--------|---|---|---|---|---|---|---|
| | a | b | c | d | e | f | g |
| Dist | 0 | 1 | 1 | 1 | 2 | 2 | 3 |
| Parent | - | a | a | a | b | c | e |



Implementation

```
0 // Credit: Competitive Programming 3
1 vi dist(V, INF); dist[s] = 0;
2 queue<int> q; q.push(s);
3 vi parent;
4 while (!q.empty()) {
5     int u = q.front(); q.pop();
6     for (int j = 0; j < (int)AdjList[u].size(); j++) {
7         ii v = AdjList[u][j];
8         if (dist[v.first] == INF) {
9             dist[v.first] = dist[u] + 1;
10            parent[v.first] = u;
11            q.push(v.first);
12 } } }
```